

Snowball problem - two competing models.

(1) Volume $\downarrow \propto$ S.A.

$$\text{IVP } \begin{cases} \frac{dr}{dt} = -k \\ r(0) = 4 \text{ in} \end{cases}$$

(2) Radius $\downarrow \propto$ S.A.

$$\text{IVP } \begin{cases} \frac{dr}{dt} = -2\pi kr^2 \\ r(0) = 4 \text{ in} \end{cases}$$

Solutions

$$(1) r(t) = (4 - kt) \text{ in}$$

$$\text{since } r(30) = 3, k = \frac{1}{30}$$

$$\Rightarrow \boxed{r(t) = 4 - \frac{t}{30} \text{ in}}$$

* By separation of vars. OR IF.

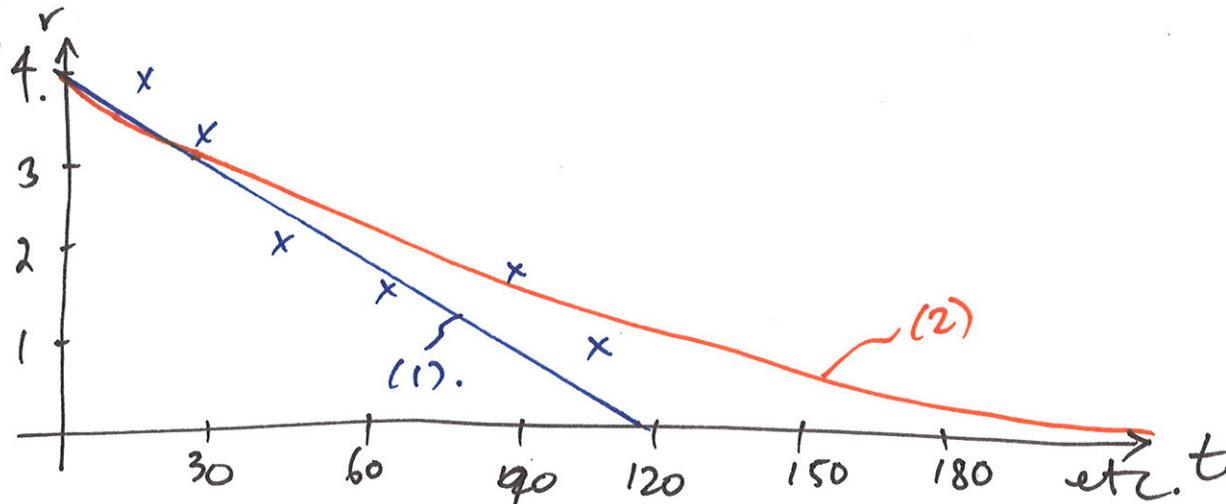
$$(2) r(t) = \frac{4}{18 + 16\pi kt}$$

$$\text{since } r(30) = 3, k = \frac{1}{120\pi}$$

$$\Rightarrow \boxed{r(t) = \frac{360}{t + 90}}$$

* By separation of variables.

Plot both solutions:



In "real life"

- Fit model (determine k) based on many data points, not just one.
- Prefer model that compares (according to some statistical measurement)

with data.

Always be clear about assumptions.

- heating constant at all times and the same in all directions.
- always spherical!
- etc.

We created a model for snowball melting via 1st order differential eqs.

Second Order Differential Equations:

(intro → 3.1, a little 3.2).

Second order DE - of the form

$$\frac{d^2y}{dt^2} = f(t, y, \frac{dy}{dt}) \quad \begin{matrix} \text{(highest derivative)} \\ \text{is second order} \end{matrix}$$

LINEAR second order DEs.

if $f(t, y, \frac{dy}{dt}) = g(t) - p(t)\frac{dy}{dt} - q(t)y$.

"standard form"

$$\frac{d^2y}{dt^2} + p(t)\frac{dy}{dt} + q(t)y = g(t).$$

NOTE: if eq. looks like

$$P(t) \frac{d^2y}{dt^2} + Q(t) \frac{dy}{dt} + R(t)y = G(t)$$

recover standard form by $\div P(t)$.

NONLINEAR second order DEs :

As before, contains non linearities in "y" terms; can't be put in standard form.

e.g.) $y \frac{d^2y}{dt^2} + 3y = t$ is nonlinear
(b/c of $y \frac{d^2y}{dt^2}$ term).

Note: HARD to solve. Often solved using numerical or graphical means.

We'll look at these LATER.

HOMOGENEOUS 2nd order Linear DEs

if $g(t) = 0$.

That is,

$$\frac{d^2y}{dt^2} + p(t) \frac{dy}{dt} + q(t)y = 0$$

is a homogeneous 2nd order linear differential eq.

2nd order DE as a from a LINEAR OPERATOR.

An operator maps one function (or vector) onto another.
(★ *VERY* loose definition).

Here, our operator is

$$\underbrace{L[\cdot]}_{\text{notation}} = \left(\frac{d^2}{dt^2} + p(t) \frac{d}{dt} + q(t) \right). \star$$

$$L[y] = \frac{d^2y}{dt^2} + p(t) \frac{dy}{dt} + q(t)y$$

e.g.] if $p(t) = 0$, $q(t) = 3t$, $y(t) = \text{cost}$.

$$\begin{aligned} L[\text{cost}] &= \frac{d^2}{dt^2}(\text{cost}) + (0) \cdot \frac{d}{dt}(\text{cost}) + (3t) \cdot \text{cost} \\ &= (3t - 1) \text{cost}. \end{aligned}$$

$L: \text{cost} \rightarrow (3t - 1) \text{cost}$.

$$\Rightarrow L[\cdot] = \left(\frac{d^2}{dt^2} + 3t \cancel{\text{cost}} \right)$$

We'll usually see

$$L[y] = 0 \quad \text{or} \quad L[y] = g(t)$$

and be asked to solve for y .

$L[\cdot]$ above $(*)$ is a LINEAR operator.

i.e. $L[\alpha y_1(t) + \beta y_2(t)]$
 $= \alpha L[y_1(t)] + \beta L[y_2(t)].$

Showing $\#$ this: $\star \alpha, \beta$ are constants

$$L[\alpha y_1(t) + \beta y_2(t)] =$$

$$\begin{aligned} &= \left[\frac{d^2}{dt^2}(\alpha y_1(t) + \beta y_2(t)) + p(t) \frac{d}{dt}(\alpha y_1(t) + \beta y_2(t)) \right. \\ &\quad \left. + q(t)(\alpha y_1(t) + \beta y_2(t)) \right] \\ &= \underbrace{\alpha \left\{ \frac{d^2 y_1}{dt^2} + p(t) \frac{dy_1}{dt} + q(t)y_1 \right\}}_{\frac{d^2}{dt^2}(\alpha y_1)} + \underbrace{\beta \left\{ \frac{d^2 y_2}{dt^2} + p(t) \frac{dy_2}{dt} + q(t)y_2 \right\}}_{\frac{d^2}{dt^2}(\beta y_2)} \\ &\rightarrow \frac{d^2}{dt^2}(\alpha y_1 + \beta y_2) = \frac{d^2}{dt^2}(\alpha y_1) + \frac{d^2}{dt^2}(\beta y_2) \\ &= \alpha \frac{d^2 y_1}{dt^2} + \beta \frac{d^2 y_2}{dt^2}. \quad \text{RL}[y_2] \\ &\rightarrow \alpha L[y_1] \end{aligned}$$

$$= \alpha L[y_1] + \beta L[y_2].$$

Next couple of weeks:

focus on case where $p(t)$, $q(t)$,
or $P(t)$, $Q(t)$, $R(t)$ are constant.

That is, eqs of the form

$$\left[a \frac{d^2y}{dt^2} + b \frac{dy}{dt} + cy = 0 \right]$$

homogeneous eq. w/ constant
coefficients.

How are we going to solve these?

By assuming that e^{rt} solves
the equation for some constant r ,
plugging in, and solving for r .

Eg) $y'' - 4y = 0$.

Assume e^{rt} solves this.

~~so y~~

Plug in:

$$y = e^{rt}, \quad y' = re^{rt}, \quad y'' = r^2 e^{rt}.$$

$$\Rightarrow y'' - 4y = 0$$

$$\text{becomes } (r^2 e^{rt}) - 4(e^{rt}) = 0$$

$$\text{want } r. \text{ Factor: } e^{rt}(r^2 - 4) = 0.$$

$$\text{since } e^{rt} \neq 0, \quad r^2 - 4 = 0$$

$$\text{or } \boxed{r = \pm 2}$$

That means both
 e^{2t} and e^{-2t}

solve this DE.

But what's the general solution?

→ Need a theorem, next time.